



# Validation of the JPSS NOAA-Unique CrIS/ATMS Processing System (NUCAPS) Operational EDR

**Nicholas R. Nalli**<sup>1,2</sup>, A. Gambacorta<sup>3</sup>, C. Barnet<sup>3</sup>, Q. Liu<sup>2</sup>, T. Reale<sup>2</sup>,  
C. Tan<sup>1,2</sup>, F. Iturbide-Sanchez<sup>1,2</sup>, B. Sun<sup>1,2</sup>, L. Borg<sup>4</sup>, D. Tobin<sup>4</sup>, E. Joseph<sup>5</sup>,  
V. R. Morris<sup>5</sup>, A. K. Mollner<sup>6</sup>, T. King<sup>1,2</sup>, W. W. Wolf<sup>2</sup>, J. W. Smith<sup>7</sup>,  
F. Tilley<sup>1,2</sup>, D. Wolfe<sup>8</sup>, *et al.*

<sup>1</sup>IMSG, Rockville, Maryland, USA

<sup>2</sup>NOAA/NESDIS/STAR, College Park, Maryland, USA

<sup>3</sup>STC, Columbia, Maryland, USA

<sup>4</sup>University of Wisconsin-Madison, Madison, Wisconsin, USA

<sup>5</sup>Howard University, Washington, D.C., USA

<sup>6</sup>The Aerospace Corp., El Segundo, California, USA

<sup>7</sup>National Research Council, College Park, Maryland, USA

<sup>8</sup>NOAA/ESRL/PSD, Boulder, Colorado, USA

**AMS Annual Meeting**

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- **JPSS Sounder EDR Cal/Val Overview**

- JPSS EDR validation
- CrIS/ATMS (CrIMSS) Sounder Operational EDR
  - NOAA-Unique CrIS/ATMS Processing System (NUCAPS)
- JPSS Level 1 Requirements
- Validation Methodology
  - Validation “Hierarchy”
  - Statistical Metrics
- JPSS S-NPP Validation Datasets
  - STAR Validation Archive (VALAR)
  - NOAA Products Validation System (NPROVS/NPROVS+)

- **NUCAPS EDR Product Validation**

- Temperature and Moisture (AVTP and AVMP) EDR
- Trace Gas
  - Ozone profile EDR
- Long-Term Monitoring (LTM)

- **Future Work**

- SNPP ICV and LTM



Validation of NOAA-Unique Operational Sounder EDR

# JPSS SOUNDER EDR CAL/VAL OVERVIEW

# Intro: JPSS Sounder EDR Validation



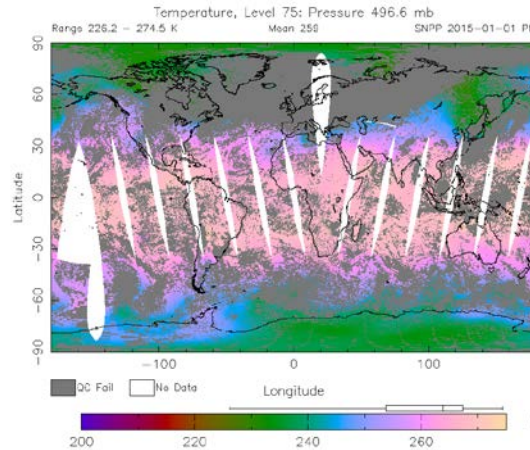
- **Validation** is “the process of ascribing uncertainties to these radiances and retrieved quantities through comparison with correlative observations” (*Fetzer et al., 2003*).
  - EDR validation supports validation of SDRs and cloud-cleared radiances (a Level 2 product shown to have positive impact on NWP; e.g., *Le Marshall et al., 2008*)
  - EDR validation enables development/improvement of algorithms
- **Users of sounder EDR observations** (AVTP, AVMP and trace gas) include
  - Weather Forecast Offices (AWIPS)
    - Nowcasting / severe weather
  - NOAA Data Centers (e.g., NGDC, CLASS)
  - Basic and applied science research/investigation (e.g., *Pagano et al., 2013*)
- **JPSS Cal/Val Phases**
  - Pre-Launch / Early Orbit Checkout (EOC)
  - **Intensive Cal/Val (ICV)**
    - Validation of EDRs against multiple correlative datasets
  - **Long-Term Monitoring (LTM)**
    - Characterization of all EDR products and long-term demonstration of performance
- In accordance with the JPSS phased schedule, the **SNPP CrIMSS EDR cal/val plan** was devised to ensure the EDR would meet the mission **Level 1 requirements** (*Barnet, 2009*)
- The **EDR validation methodology** draws upon previous work with AIRS and IASI (*Nalli et al., 2013, JGR Special Section on SNPP Cal/Val*)
  - Classification of various approaches into a “Validation Methodology Hierarchy”

# CrIS/ATMS (CrIMSS) Sounder Operational EDR: NOAA Unique CrIS/ATMS Processing System (NUCAPS)

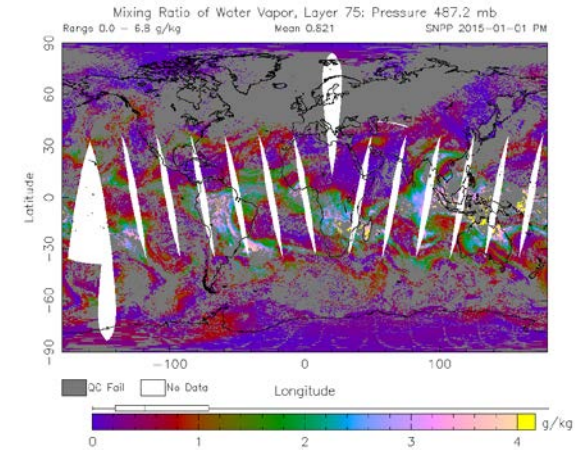


- **Original IDPS Algorithm**
  - Optimal Estimation (OE) algorithm originally developed by AER, LaRC and NGAS
  - CrIMSS operational product (MX7.1) validated through Beta and Provisional Maturities (*Divakarla et al., 2014*)
  
- **NUCAPS Algorithm** (*Gambacorta et al. 2014*)
  - **Operational algorithm beginning Sep 2013**
    - Transition to NUCAPS validation
    - **Stage-1 Validated Maturity achieved in Sep 2014**
  - Line-for-line modular implementation of the iterative, multistep AIRS Science Team retrieval algorithm
  - Non-precipitating conditions (cloudy, partly cloudy, clear)
  - Atmospheric Vertical Temperature, Moisture (AVTP, AVMP) and trace gas profiles ( $O_3$ , CO,  $CO_2$ ,  $CH_4$ )

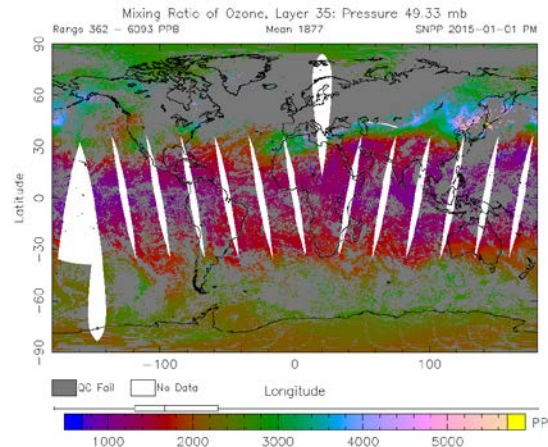
**NUCAPS AVTP**



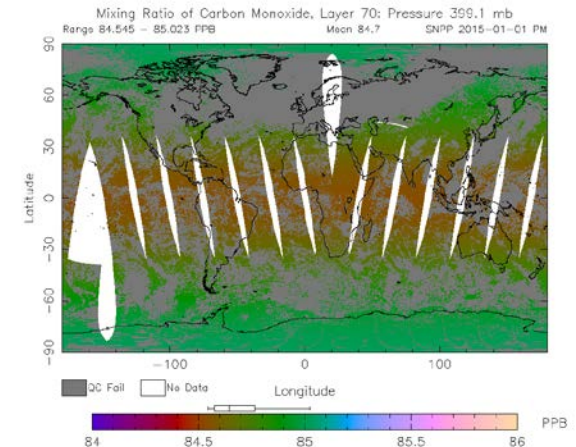
**NUCAPS AVMP**



**NUCAPS  $O_3$**



**NUCAPS CO**



<http://www.ospo.noaa.gov/Products/atmosphere/soundings/nucaps/index.html>

# CrIS/ATMS Sounder EDR L1 Requirements



## AVTP and AVMP EDR

CrIS/ATMS Atmospheric Vertical Temperature Profile (AVTP) Measurement Uncertainty – Layer Average Temperature Error	
PARAMETER	THRESHOLD
AVTP, Cloud fraction < 50%, surface to 300 hPa	1.6 K / 1-km layer
AVTP, Cloud fraction < 50%, 300–30 hPa	1.5 K / 3-km layer
AVTP, Cloud fraction < 50%, 30–1 hPa	1.5 K / 5-km layer
AVTP, Cloud fraction < 50%, 1–0.5 hPa	3.5 K / 5-km layer
AVTP, Cloud fraction ≥ 50%, surface to 700 hPa	2.5 K / 1-km layer
AVTP, Cloud fraction ≥ 50%, 700–300 hPa	1.5 K / 1-km layer
AVTP, Cloud fraction ≥ 50%, 300–30 hPa	1.5 K / 3-km layer
AVTP, Cloud fraction ≥ 50%, 30–1 hPa	1.5 K / 5-km layer
AVTP, Cloud fraction ≥ 50%, 1–0.5 hPa	3.5 K / 5-km layer

CrIS/ATMS Atmospheric Vertical Moisture Profile (AVMP) Measurement Uncertainty – 2-km Layer Average Mixing Ratio % Error	
PARAMETER	THRESHOLD
AVMP, Cloud fraction < 50%, surface to 600 hPa	Greater of 20% or 0.2 g·kg <sup>-1</sup> / 2-km layer
AVMP, Cloud fraction < 50%, 600–300 hPa	Greater of 35% or 0.1 g·kg <sup>-1</sup> / 2-km layer
AVMP, Cloud fraction < 50%, 300–100 hPa	Greater of 35% or 0.1 g·kg <sup>-1</sup> / 2-km layer
AVMP, Cloud fraction ≥ 50%, surface to 600 hPa	Greater of 20% of 0.2 g·kg <sup>-1</sup> / 2-km layer
AVMP, Cloud fraction ≥ 50%, 600–400 hPa	Greater of 40% or 0.1 g·kg <sup>-1</sup> / 2-km layer
AVMP, Cloud fraction ≥ 50%, 400–100 hPa	Greater of 40% or 0.1 g·kg <sup>-1</sup> / 2-km layer

Source: L1RD (2014), pp. 41, 43

## Trace Gas EDR

CrIS Infrared Trace Gases Specification Performance Requirements	
PARAMETER	THRESHOLD
CO (Carbon Monoxide) Total Column Precision	35%, or full res mode 15%
CO (Carbon Monoxide) Total Column Accuracy	±25%, or full res mode ±5%
CO <sub>2</sub> (Carbon Dioxide) Total Column Precision	0.5% (2 ppmv)
CO <sub>2</sub> (Carbon Dioxide) Total Column Accuracy	±1% (4 ppmv)
CH <sub>4</sub> (Methane) Total Column Precision	1% (≈20 ppbv)
CH <sub>4</sub> (Methane) Total Column Accuracy	±4% (≈80 ppbv)
O <sub>3</sub> (Ozone) Profile Precision, 4–260 hPa (6 statistic layers)	20%
O <sub>3</sub> (Ozone) Profile Precision, 260 hPa to sfc (1 statistic layer)	20%
O <sub>3</sub> (Ozone) Profile Accuracy, 4–260 hPa (6 statistic layers)	±10%
O <sub>3</sub> (Ozone) Profile Accuracy, 260 hPa to sfc (1 statistic layer)	±10%
O <sub>3</sub> (Ozone) Profile Uncertainty, 4–260 hPa (6 statistic layers)	25%
O <sub>3</sub> (Ozone) Profile Uncertainty, 260 hPa to sfc (1 statistic layer)	25%

Source: L1RD (2014), pp. 45-49

**Global requirements defined for lower and upper atmosphere subdivided into 1-km and 2-km layers for AVTP and AVMP, respectively.**

# Validation Methodology Hierarchy

(e.g., Nalli et al., 2013)



## 1. Numerical Model (e.g., ECMWF, NCEP/GFS) Global Comparisons

- Large, truly global samples acquired from Focus Days
- Useful for early sanity checks, bias tuning and regression
- However, not independent truth data

## 2. Satellite EDR (e.g., AIRS, ATOVS, COSMIC) Intercomparisons

- Global samples acquired from Focus Days (e.g., AIRS)
- Consistency checks; merits of different retrieval algorithms
- However, IR sounders have similar error characteristics; must take rigorous account of averaging kernels of both systems (e.g., Rodgers and Connor, 2003)

## 3. Conventional RAOB Matchup Assessments

- WMO/GTS operational sondes launched ~2/day for NWP
- Useful for representation of global zones and long-term monitoring
- Large statistical samples acquired after a couple months' accumulation (e.g., Divakarla et al., 2006)
- NOAA Products Validation System (NPROVS) (Reale et al., 2012)
- Limitations:
  - Skewed distribution toward NH-continental sites
  - Mismatch errors, potentially systematic at individual sites
  - Non-uniform, less-accurate and poorly characterized radiosondes
  - RAOBs assimilated, by definition, into numerical models

## 4. Dedicated/Reference RAOB Matchup Assessments

- *Dedicated* for the purpose of satellite validation
  - Well-specified error characteristics and optimal accuracy
  - Minimal mismatch errors
  - Include atmospheric state “best estimates” or “merged soundings”
- Reference sondes: CFH, corrected RS92
  - Traceable measurement
- Detailed performance specification and regional characterization
- Limitation: Small sample sizes and geographic coverage
- E.g., **ARM sites** (e.g., Tobin et al., 2006), AEROSE, ideally GRUAN

## 5. Intensive Field Campaign Dissections

- Include dedicated RAOBs, especially those *not* assimilated into NWP models
- Include ancillary datasets (e.g., ozonesondes, lidar, M-AERI, MWR, sunphotometer, etc.)
- Ideally include funded aircraft campaign using IR sounder (e.g., NAST-I, S-HIS)
- Detailed performance specification; state specification; SDR cal/val; EDR “dissections”
- E.g., **AEROSE, CalWater2, JAIVEX, WAVES, AWEX-G, EAQUATE**

# Assessment Methodology: Statistical Metrics



- Level 1 AVTP and AVMP accuracy requirements are defined over **coarse layers**, roughly 1–5 km for tropospheric AVTP and 2 km for AVMP (Table, Slide 5).
- We have recently introduced rigorous **geographic surface area weighting** to these schemes for dedicated/reference RAOB samples

## AVTP

$$\text{RMS}(\Delta T_{\mathcal{L}}) = \sqrt{\frac{1}{n_j} \sum_{j=1}^{n_j} (\Delta T_{\mathcal{L},j})^2} \quad \text{BIAS}(\Delta T_{\mathcal{L}}) \equiv \overline{\Delta T_{\mathcal{L}}} = \frac{1}{n_j} \sum_{j=1}^{n_j} \Delta T_{\mathcal{L},j}$$

$$\text{STD}(\Delta T_{\mathcal{L}}) \equiv \sigma(\Delta T_{\mathcal{L}}) = \sqrt{[\text{RMS}(\Delta T_{\mathcal{L}})]^2 - [\text{BIAS}(\Delta T_{\mathcal{L}})]^2}$$

## AVMP and O<sub>3</sub>

- W2 weighting was used in determining Level 1 Requirements
- To allow compatible STD calculation, W2 weighting should be consistently used for both RMS and BIAS

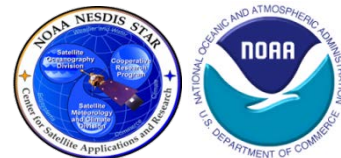
$$\Delta q_{\mathcal{L},j} \equiv \frac{\hat{q}_{\mathcal{L},j} - q_{\mathcal{L},j}}{q_{\mathcal{L},j}} \quad \text{RMS}(\Delta q_{\mathcal{L}}) = \sqrt{\frac{\sum_{j=1}^{n_j} W_{\mathcal{L},j} (\Delta q_{\mathcal{L},j})^2}{\sum_{j=1}^{n_j} W_{\mathcal{L},j}}}, \quad \text{water vapor weighting factor, } W_{\mathcal{L},j},$$

$$\text{BIAS}(\Delta q_{\mathcal{L}}) = \frac{\sum_{j=1}^{n_j} W_{\mathcal{L},j} \Delta q_{\mathcal{L},j}}{\sum_{j=1}^{n_j} W_{\mathcal{L},j}}, \quad W_{\mathcal{L},j} = \begin{cases} 1 & , W^0 \\ q_{\mathcal{L},j} & , W^1 \\ (q_{\mathcal{L},j})^2 & , W^2 \end{cases}$$

$$\text{STD}(\Delta q_{\mathcal{L}}) = \sqrt{[\text{RMS}(\Delta q_{\mathcal{L}})]^2 - [\text{BIAS}(\Delta q_{\mathcal{L}})]^2}$$

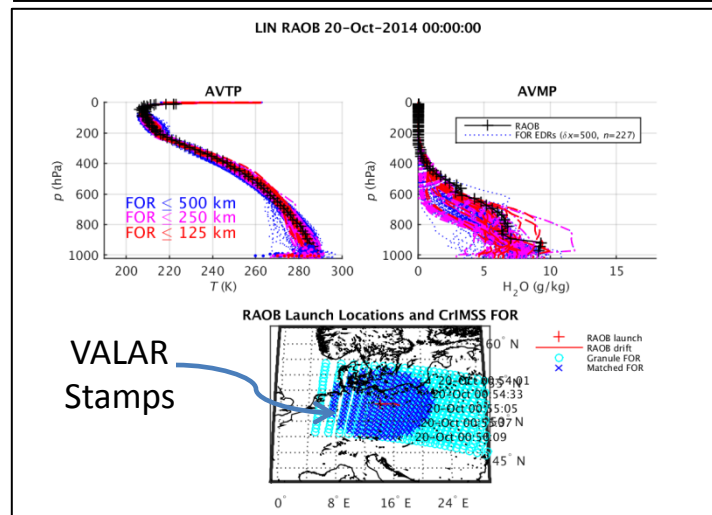
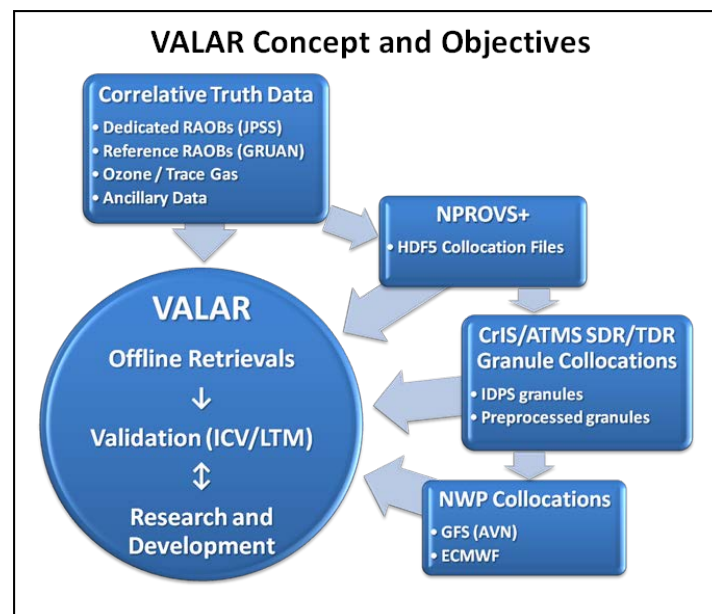


# JPSS SNPP Validation Datasets and Tools

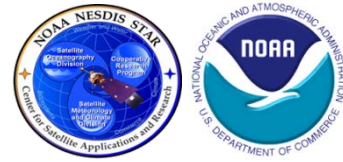


- **STAR Validation Archive (VALAR)** (*Nalli et al., 2014*)
  - Low-level research archive designed to meet needs of Cal/Val Plan
  - Dedicated/reference and intensive campaign RAOBs
  - SDR/TDR granule-based collocations (“stamps”) within 500 km radius acquired off SCDR (past 90 days) or CLASS (older than 90 days)
  - Basis for Trace Gas EDR validation
  - Offline retrievals / retrospective reprocessing
  - MATLAB and IDL statistical codes and visualization software tools for monitoring
  - Rigorous coarse-layer (1-km, 2-km) product performance measures based on statistical metrics corresponding to Level 1 Requirements detailed in *Nalli et al. (2013)*

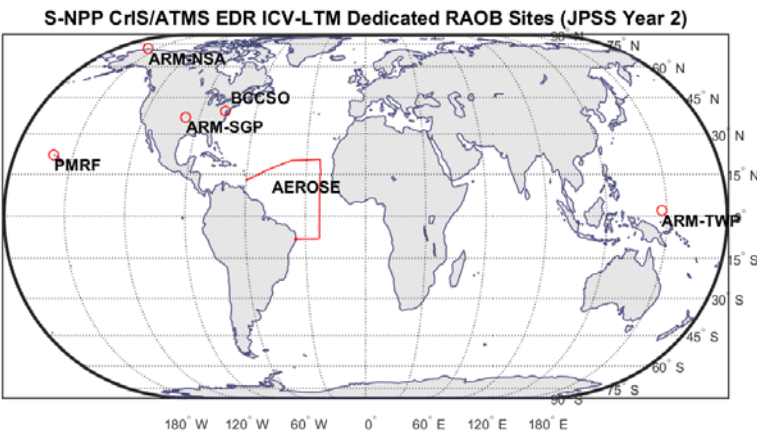
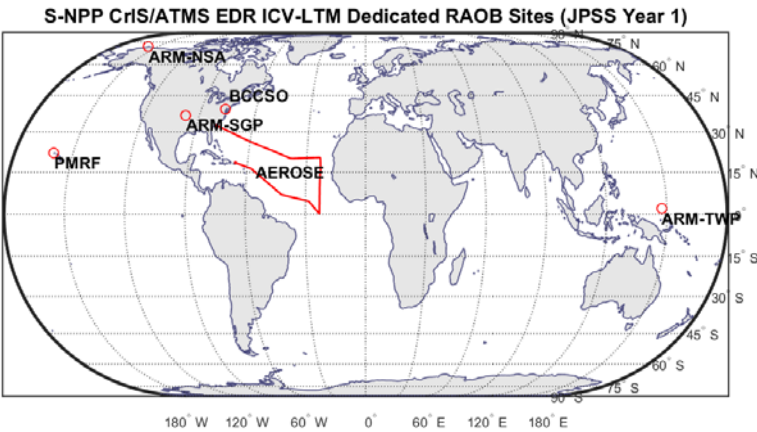
- **NOAA Products Validation System (NPROVS)** (*Reale et al., 2012*)
  - Conventional RAOBs (NPROVS+ dedicated/reference), “single closest FOR” collocations
  - HDF5-formatted Collocation Files facilitates GRUAN RAOB matchups within VALAR
  - NRT monitoring capability
  - Satellite EDR intercomparison (e.g., *Nalli et al. 2013*) capability
  - Java based graphical user interface tools for monitoring
    - Profile Display (PDISP)
    - NPROVS Archive Summary (NARCS)



# VALAR Dedicated and Reference RAOBs

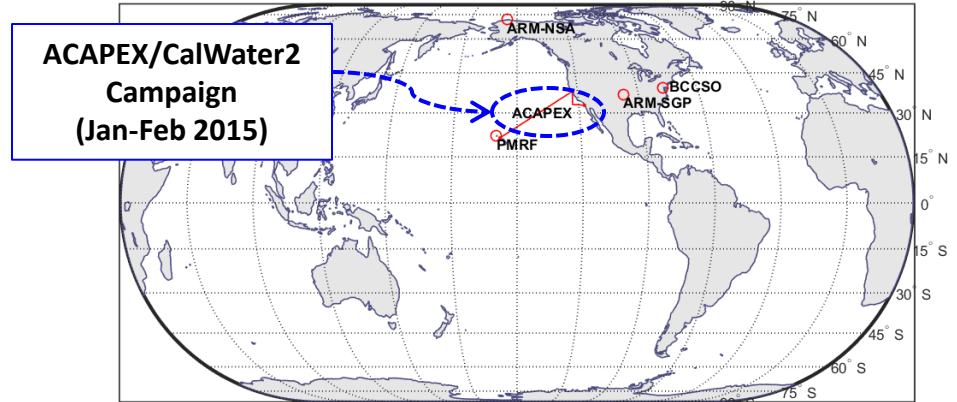


## JPSS S-NPP Dedicated Years 1 and 2 (2012-2014)

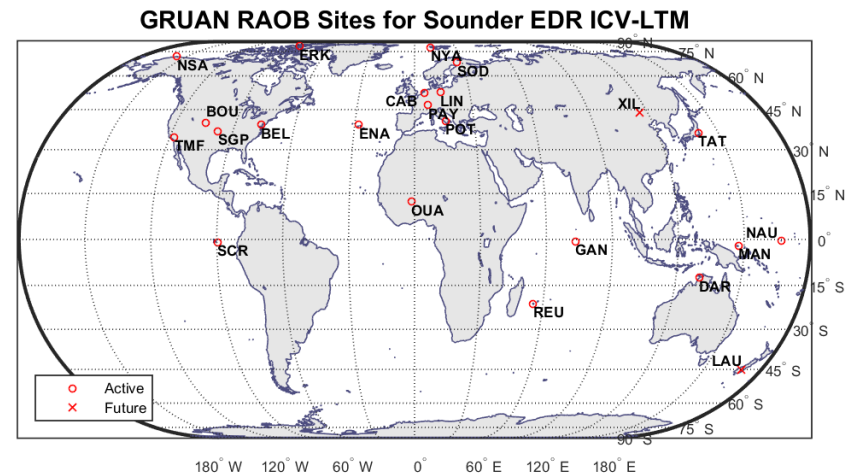


## JPSS S-NPP Dedicated Year 3 (2014-2015)

S-NPP CrIS/ATMS EDR ICV-LTM Dedicated RAOB Sites (JPSS Year 3)



## GRUAN Reference Sites (NPROVS+ Collocation)



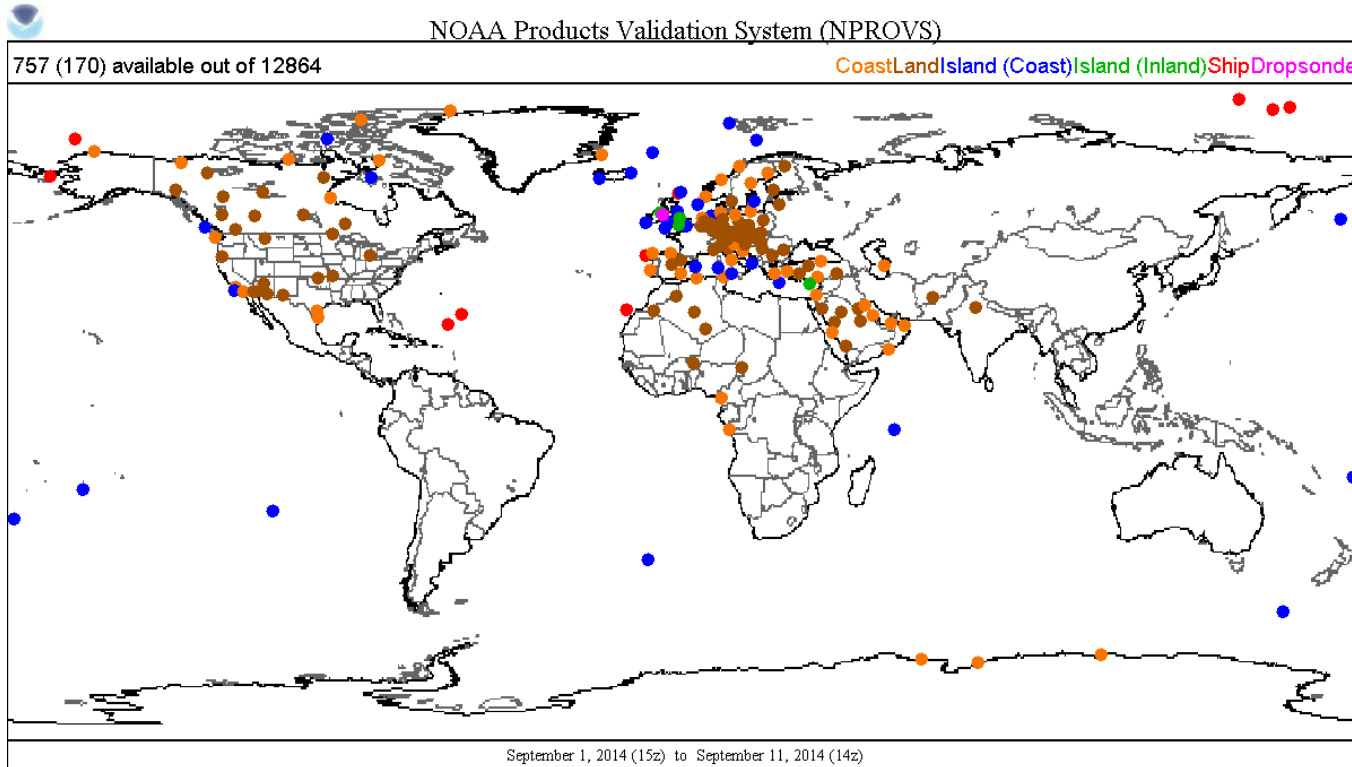


Validation of NOAA-Unique Operational Sounder EDR

# NUCAPS EDR PRODUCT VALIDATION

# NPROVS Conventional RAOB Collocations

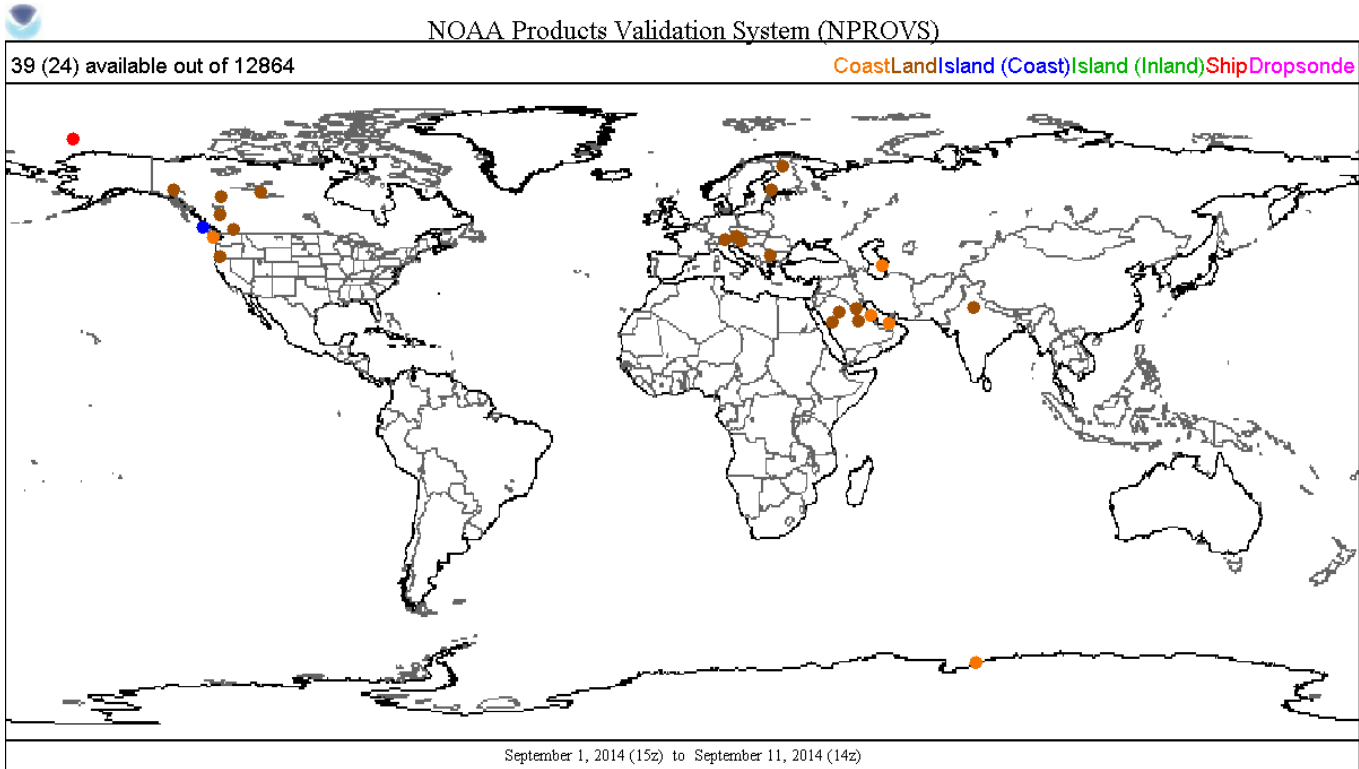
Single Closest FOR (*Reale et al., 2012*)



- 1–11 Sep 2014
- RS92 and RS41 sondes
- Single-closest FOR
- Space-time window 1
  - $\pm 3$  h before/after overpass
  - 75 km
- Sample size 1  
 $N = 757$

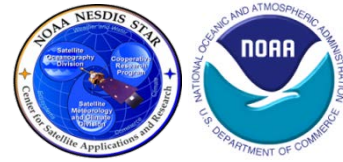
# NPROVS Conventional RAOB Collocations

Single Closest FOR (*Reale et al., 2012*)

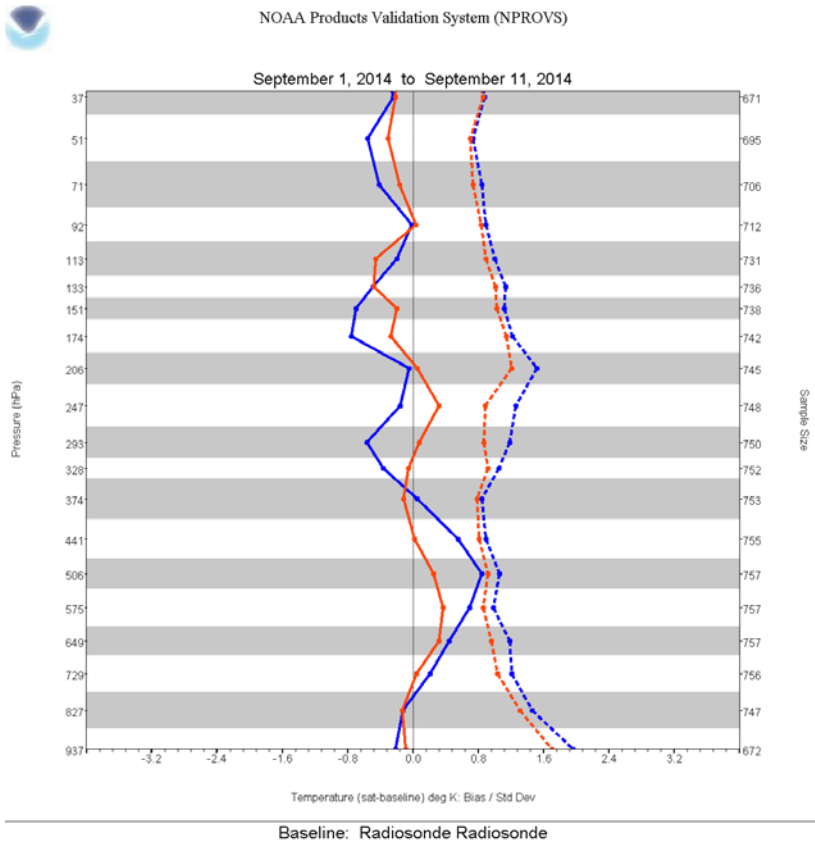


- 1–11 Sep 2014
- RS92 and RS41 sondes
- Single-closest FOR
- Space-time window 2
  - -1–0 h before overpass
  - 75 km
- Sample size 2  
 $N = 39$

# NDE-OPS NUCAPS and AIRS versus NPROVS Collocated Conventional RAOB: Sample 1



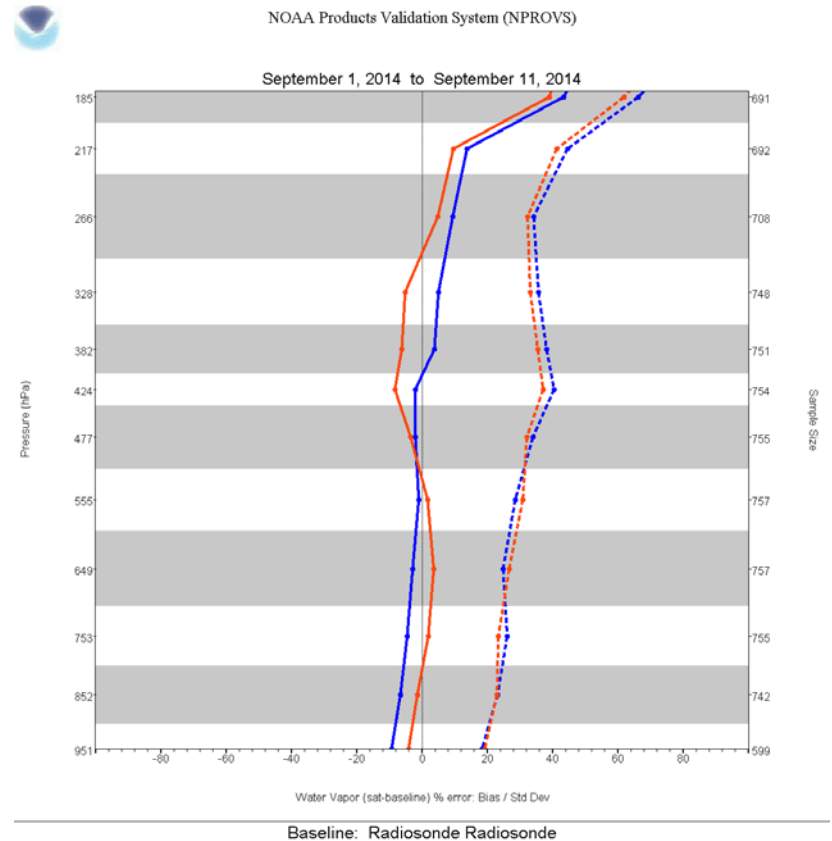
## AVTP (BIAS and RMS)



AIRS AQUA

NUCAPS NPP

## AVMP (BIAS and RMS)



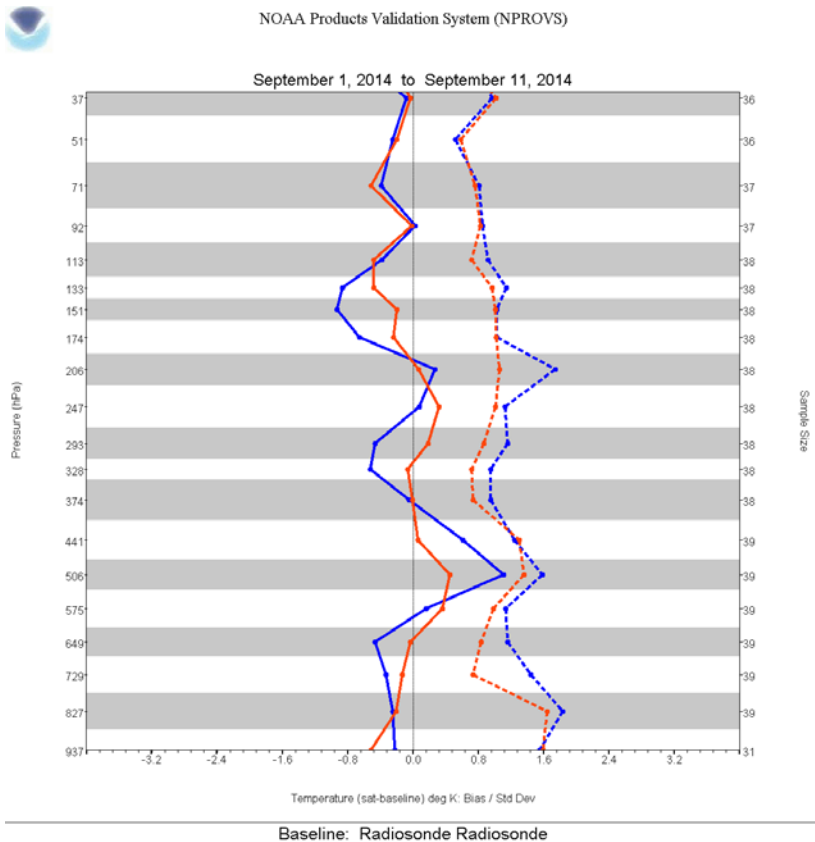
AIRS AQUA

NUCAPS NPP

# NDE-OPS NUCAPS and AIRS versus NPROVS Collocated Conventional RAOB: Sample 2



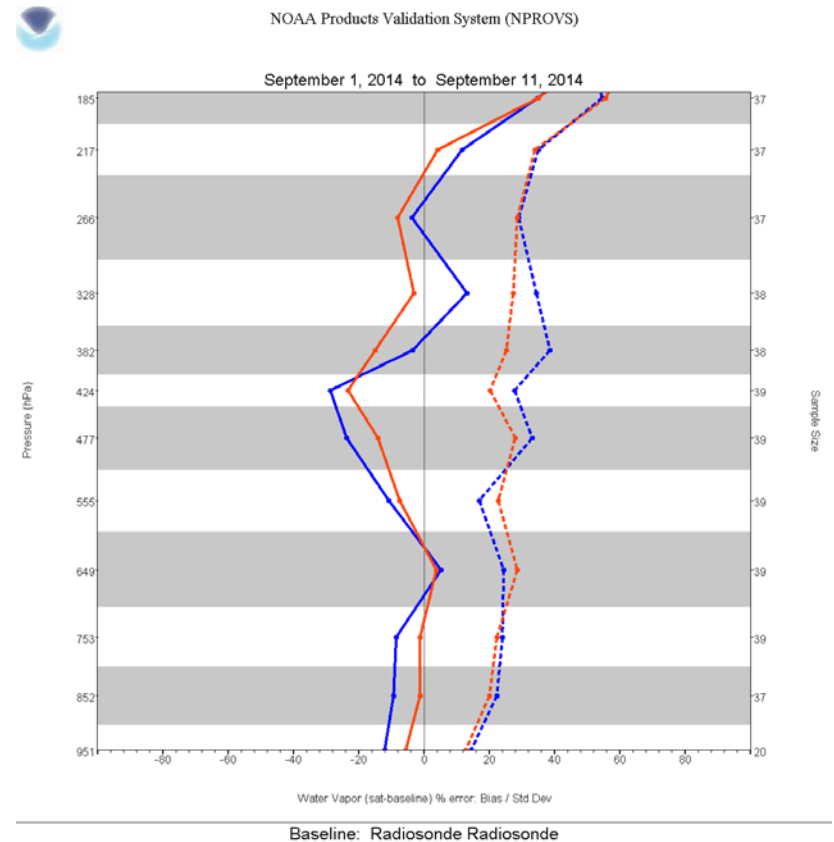
## AVTP (BIAS and RMS)



AIRS AQUA

NUCAPS NPP

## AVMP (BIAS and RMS)



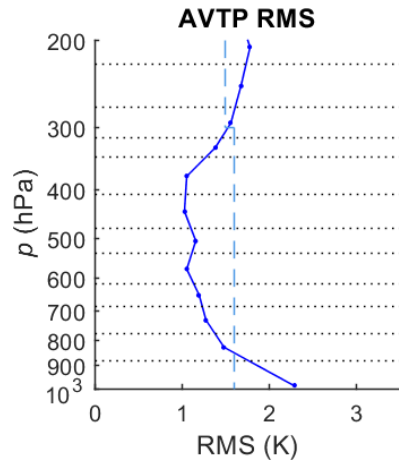
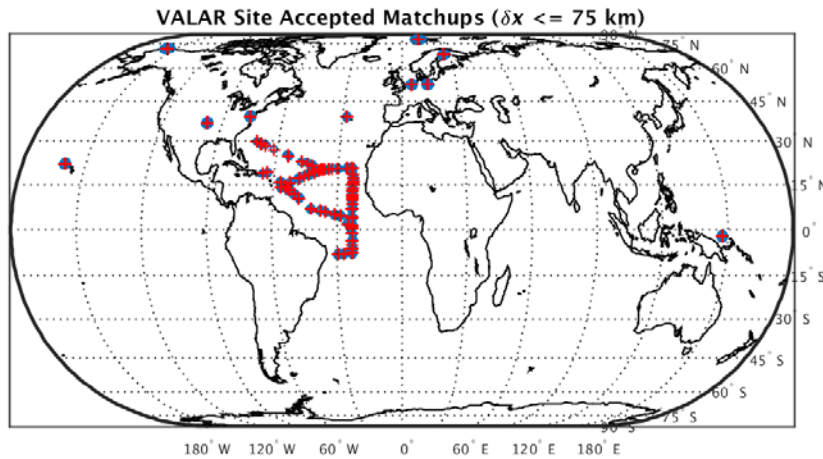
AIRS AQUA

NUCAPS NPP

# NUCAPS AVTP/AVMP (NDE-OPS) versus Dedicated/Reference RAOB Day and Night

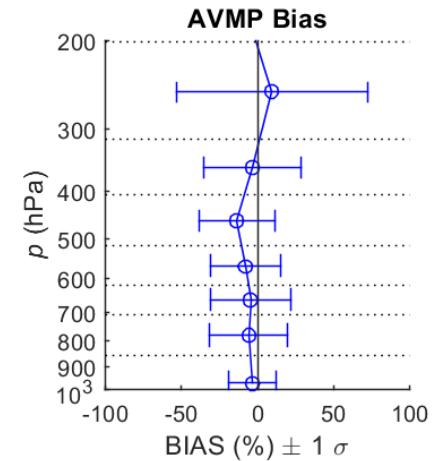
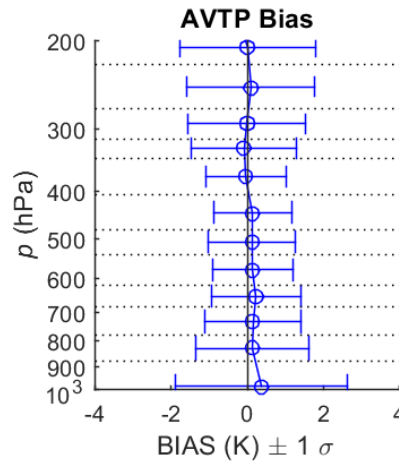
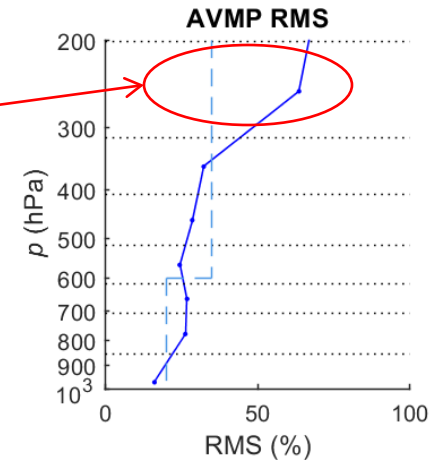


VALAR RAOB sample weighted by zonal surface areas



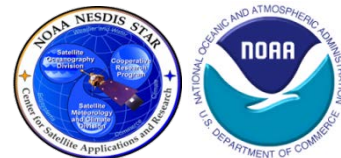
Large random error due to RAOB drift in high latitudes?

$n = 1881$

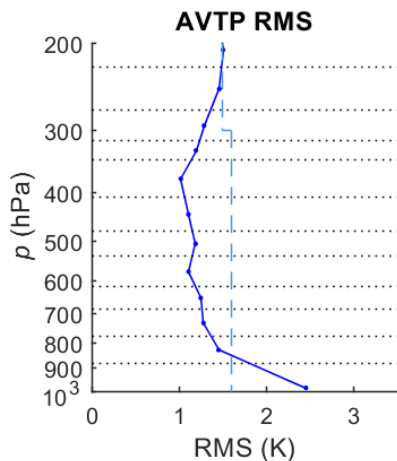
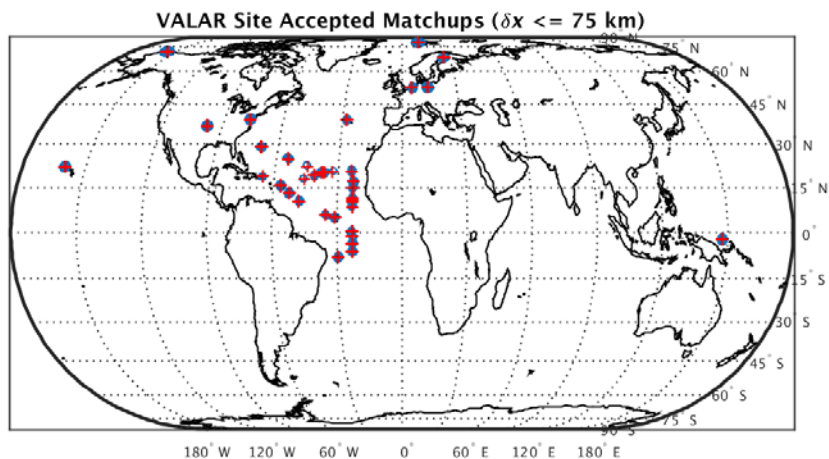




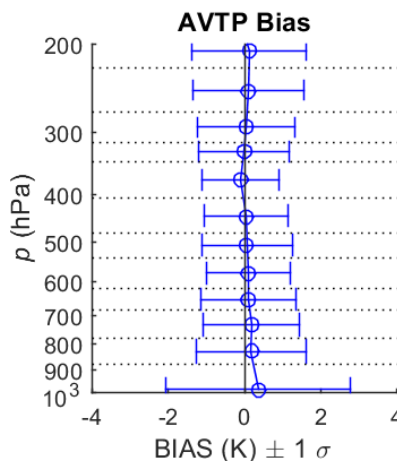
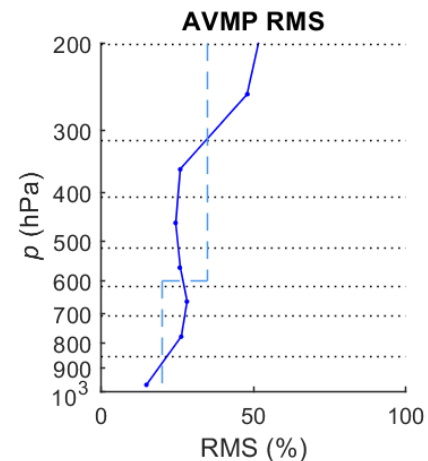
# NUCAPS AVTP/AVMP (NDE-OPS) versus Dedicated/Reference RAOB Nighttime Only



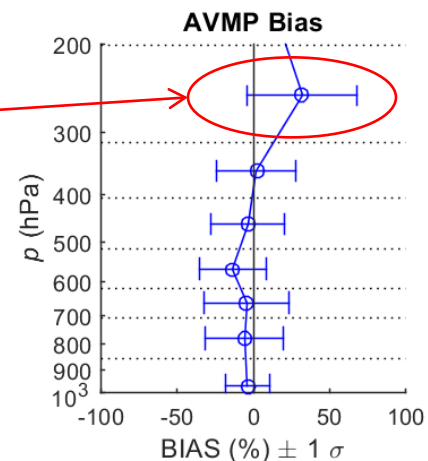
VALAR RAOB sample weighted by zonal surface areas



$n = 848$



Extreme dry  
subsidence in  
tropical sites  
(AEROSE)?



# NUCAPS Trace Gas Validation

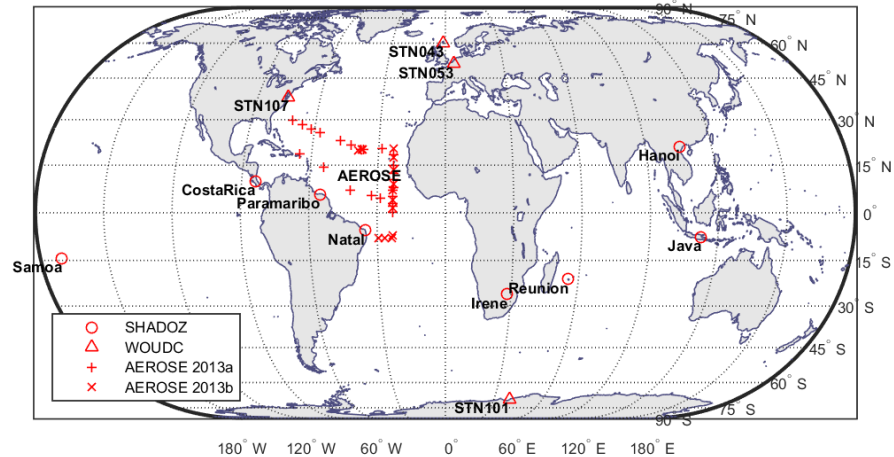


- **Validation of NUCAPS Trace Gases**

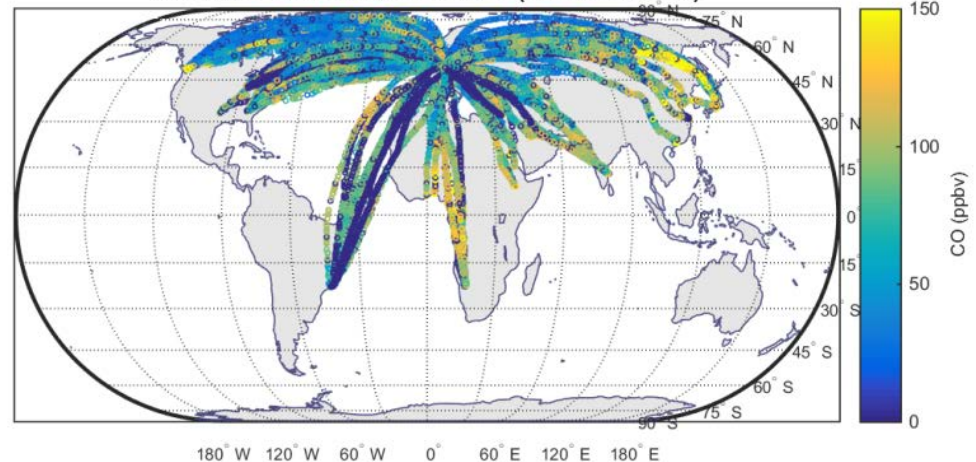
- Available *in situ* truth datasets
- Collocated ozonesondes for  $O_3$  (ozone) profile EDR
  - SHADOZ sites
  - WOUDC currently being acquired
  - AROSE and CalWater2 dedicated ozonesondes
- Collocated aircraft data for  $CO$ ,  $CO_2$ ,  $O_3$ 
  - MOZAIC
  - Additional data currently being sought

- **Comparisons of NUCAPS  $CO$  and  $O_3$**  can also be performed against models (i.e., Step 1 of Validation Hierarchy; e.g., WRF-CHEM Model, *Smith and Nalli, 2014*)

S-NPP CrIS/ATMS Ozone EDR ICV-LTM Ozonesonde Sites



MOZAIC In Situ Carbon Monoxide (Jan-12 to Jul-12)

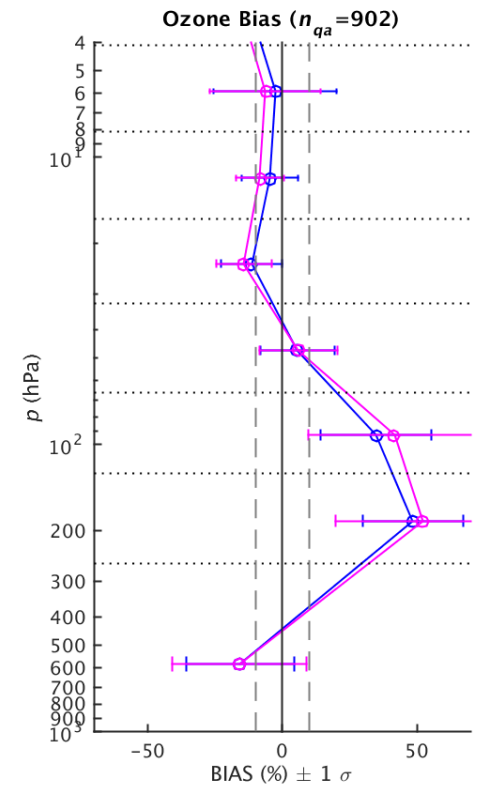
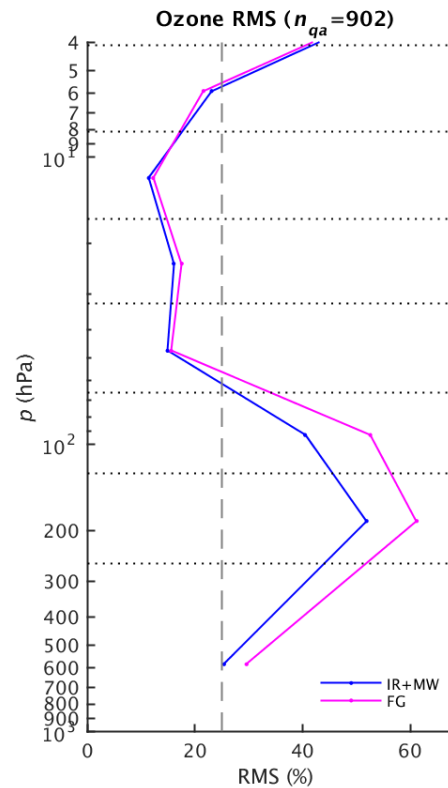
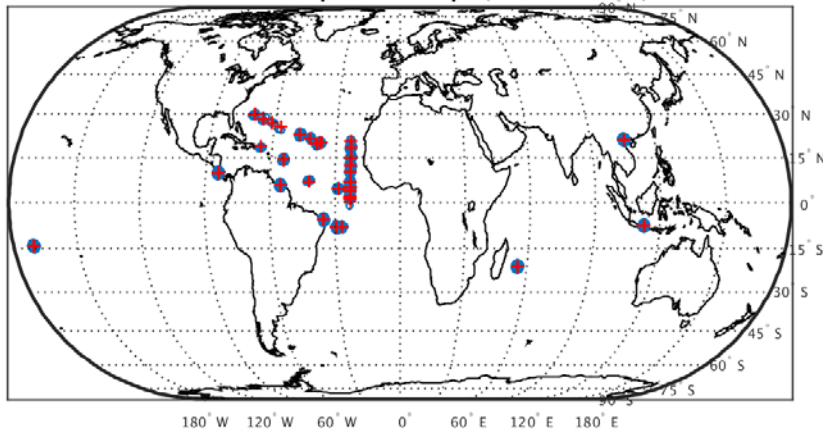


# Preliminary Ozone Profile Validation

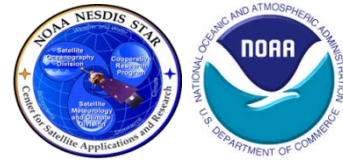


VALAR AEROSE Dedicated and SHADOZ  
Ozonesonde Sample

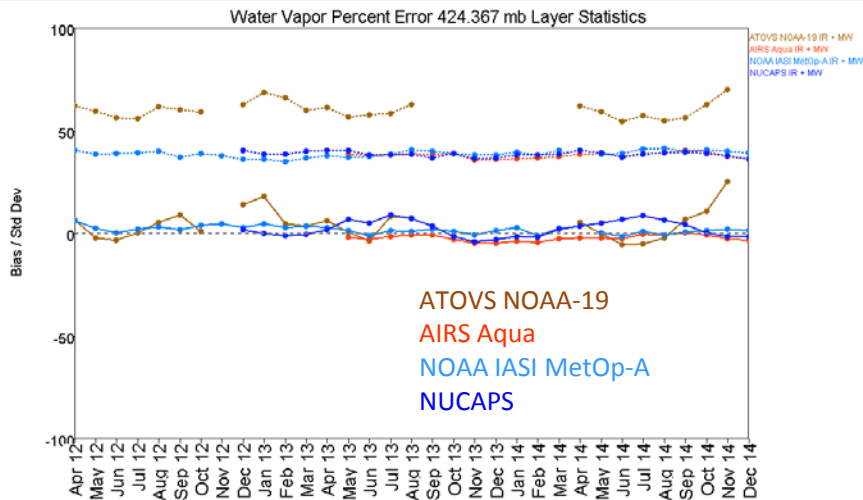
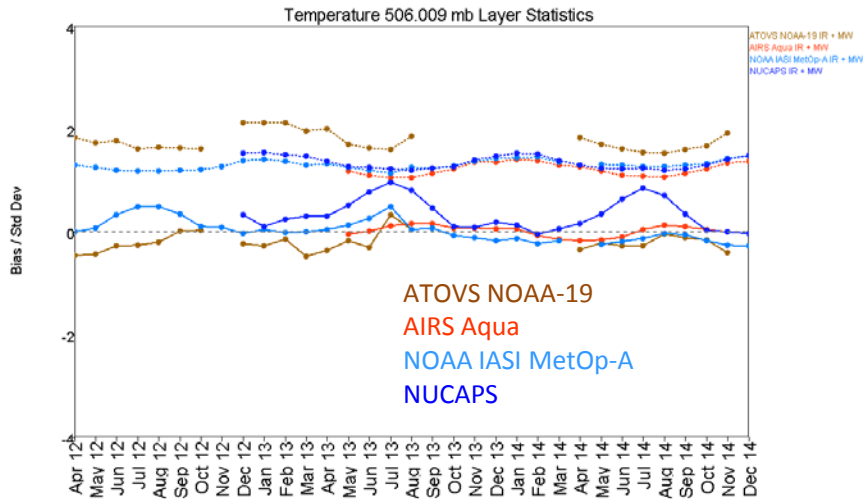
VALAR Site Accepted Matchups ( $\delta x \leq 125$  km)



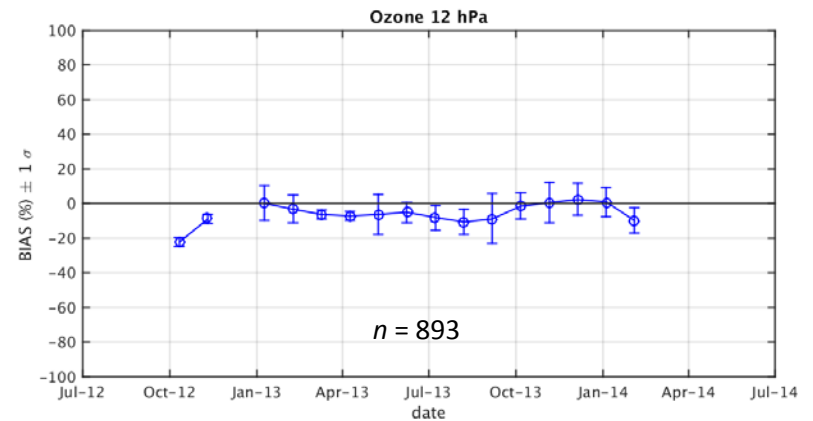
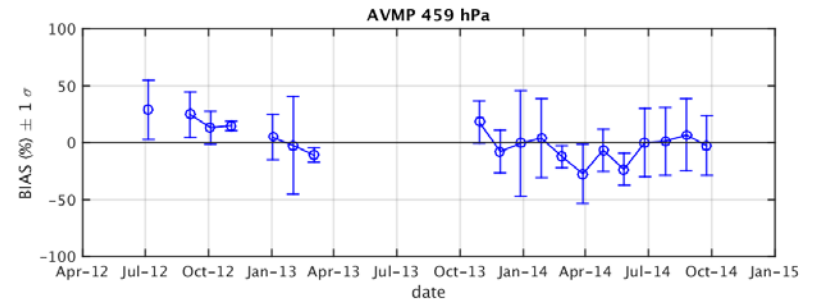
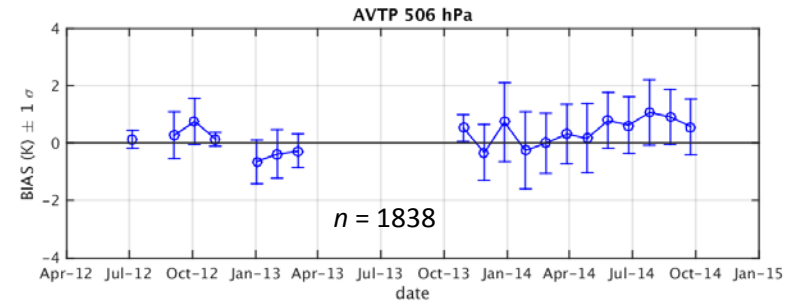
# Long-Term Monitoring (LTM)



## NPROVS NARCS Conventional RAOB Collocation

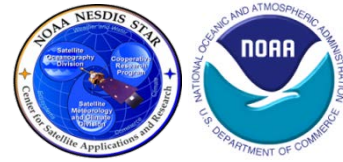


## VALAR Dedicated/GRUAN/Ozonesonde Collocation



- **NUCAPS Stages 2-3 Validated Maturities**
  - **AVTP/AVMP, Trace Gas validation** for operational and offline code versions
    - Global coarse-layer ensemble statistical analyses versus dedicated, reference and conventional RAOB truth
    - Geographic surface area weighting
    - **Apply averaging kernels** in NUCAPS error analyses, including ozone profile EDR
  - **VALAR growth, development and enhancements**
    - Support **ACAPEX/CalWater2 (Pacific Ocean, Jan-Feb 2015)** and future **AEROSE** campaigns
    - Support ARM and PMRF dedicated RAOBs (including dual-launches, “best estimates”)
    - Leverage GRUAN reference RAOBs
    - Trace gas (O<sub>3</sub>, CO, CO<sub>2</sub>) datasets
    - **GRUAN reprocessing** of RS92 RAOB data (viz., entire AEROSE data record)
  - Support short- and long-term NUCAPS EDR algorithm development, updates, improvements
  
- **Other Related Work**
  - Collocation uncertainty estimates
  - calc – obs analyses for different forward models (CRTM, LBLRTM, SARTA, etc.)
  - Support skin SST EDR validation
  - Support EDR applications (AWIPS, atmospheric chemistry users)

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# EXTRA SLIDES

# Assessment Methodology: Reducing Truth to Correlative Layers



- The **measurement equation** (e.g., *Taylor and Kuyatt, 1994*) for retrieval includes forward and inverse operators (*Rodgers, 1990*) to estimate the measurand,  $\mathbf{x}$ , on forward model layers:

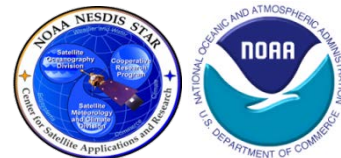
$$\hat{\mathbf{x}} = I[F(\mathbf{x}, \mathbf{b}), \mathbf{b}, \mathbf{c}]$$

- **Rigorous validation** therefore requires high-resolution truth measurements (e.g., dedicated RAOB) be **reduced to correlative RTA layers** (*Nalli et al., 2013, JGR Special Section on SNPP Cal/Val*)
- **Radiative transfer approach** is to integrate quantities over the atmospheric path (e.g., number densities  $\rightarrow$  column abundances), interpolate to RTA (arbitrary) levels, then compute RTA layer quantities, e.g.,

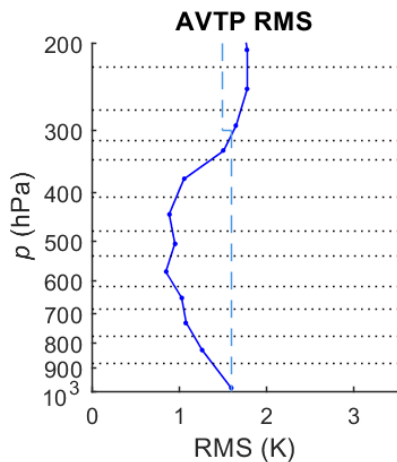
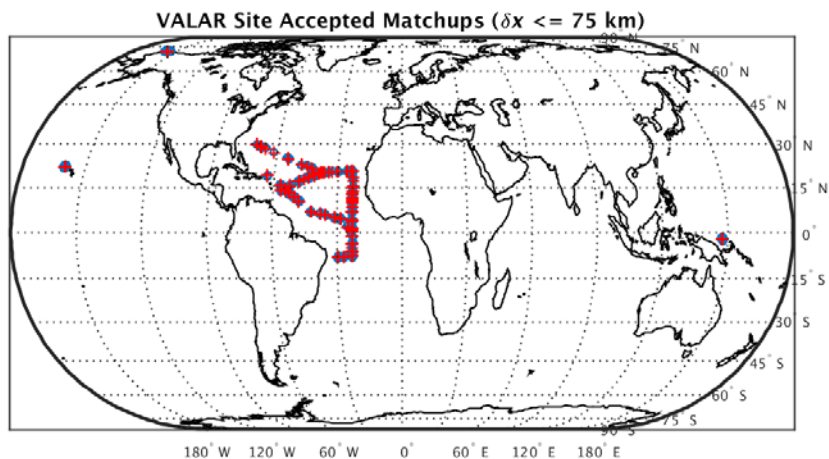
$$\sum_x(z) = \int_{z_t}^z N_x(z') dz'$$



# NUCAPS AVTP/AVMP (NDE-OPS) versus VALAR Dedicated RAOB Ocean Only Day and Night



RAOB sample weighted by zonal surface areas



$n = 382$

